

# Honors Multivariable Calculus : : Class 11

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Partial derivatives of  $f$  at  $\vec{a}$  with respect to  $x_i$  is

$$D_{e_i} f(\vec{a})$$

More common notation is  $\frac{\partial f}{\partial x_i}(\vec{a})$  Sometimes you will see

$$f(x, y) = z$$

So

$$\frac{\partial z}{\partial x} = f_x$$

An example can be  $f(x, y) = (\sin y + x^2 e^y, x + 2xy)$  where  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  and we want  $\frac{\partial f}{\partial x}$  at  $(2, 0)$ ?

We can do this on the long way so by definition

$$\begin{aligned} & \lim_{t \rightarrow 0} \frac{f(2, 0) + t\vec{e}_1 - f(2, 0)}{t} \\ & \lim_{t \rightarrow 0} \frac{f(2+t, 0) - f(2, 0)}{t} \\ & \lim_{t \rightarrow 0} \frac{\begin{pmatrix} 0 + (2+t)^2 \\ 2+t + 2(2+t) \cdot 0 \end{pmatrix} - \begin{pmatrix} 4 \\ 2 \end{pmatrix}}{t} \end{aligned}$$

We have a simple single variable derivative.

$$\begin{pmatrix} \lim_{t \rightarrow 0} \frac{(2+t)^2 - 4}{t} \\ \lim_{t \rightarrow 0} \frac{2+t + 2(2+t)0 - 2}{t} \end{pmatrix}$$

This just boils down into treating the individual components as individual derivatives.

$$\frac{\partial f}{\partial x}(2, 0) = \begin{pmatrix} 4 \\ 1 \end{pmatrix}$$

Just doing single variable we can find

$$\frac{\partial f}{\partial y}(2, 0) = \begin{pmatrix} 5 \\ 4 \end{pmatrix}$$

These are directional derivative along  $\vec{e}_1$  and  $\vec{e}_2$ .

$$\frac{\partial f}{\partial x}(2, 0) = \begin{pmatrix} 4 \\ 1 \end{pmatrix} = D_{\vec{e}_1} f(2, 0)$$

$$\frac{\partial f}{\partial y}(2, 0) = \begin{pmatrix} 5 \\ 4 \end{pmatrix} = D_{\vec{e}_2} f(2, 0)$$

If  $f$  is differentiable and  $df(2, 0)$  is represented by matrix  $M$  then

$$M = \begin{pmatrix} 4 & 5 \\ 1 & 4 \end{pmatrix}$$

$$df_{(2,0)}(\vec{e}_1) = M\vec{e}_1$$

$$df_{(2,0)}(\vec{e}_2) = M\vec{e}_2$$

If  $f$  is differentiable at  $\vec{a}$  then  $Mx$  for  $df_{\vec{a}}$  is

$$\left( \frac{\partial f}{\partial x_1}(\vec{a}) \quad \dots \quad \frac{\partial f}{\partial x_n}(\vec{a}) \right)$$

Consider the vertical spanning of this matrix too. We have columns here beware!

If  $f(\vec{a})$  is  $(f_1(\vec{a}), f_2(\vec{a}), \dots, f_m(\vec{a}))$  if  $f$  is differentiable at  $\vec{a}$  then

$$df_{\vec{a}} = \begin{pmatrix} \frac{\partial f_1}{\partial x_1}(\vec{a}) & \dots & \frac{\partial f_1}{\partial x_n}(\vec{a}) \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1}(\vec{a}) & \dots & \frac{\partial f_m}{\partial x_n}(\vec{a}) \end{pmatrix}$$

The  $ij$  entry is  $\frac{\partial f_i}{\partial x_j}(\vec{a})$  So  $f$  is differentiable at  $\vec{a}$ , then this means  $f$  has directional derivatives in all directions of  $\vec{a}$ , then this also means  $f$  has partial derivatives along all  $n$  basis directions.

$$f(x, y) = \sqrt{|xy|}$$

Does not have directional derivatives (wait how why)

## Partial derivatives around a region

Theorem 1. If  $\frac{\partial f_i}{\partial x_j}$  all exist on some neighborhood of  $\vec{a}$  and are continuous there (neighborhood basically means some small open set ball containing  $\vec{a}$ ), the  $f$  is differentiable at  $\vec{a}$ .

**Proof.** Lemma: If  $f : D \rightarrow \mathbb{R}^m$  and  $f(\vec{a}) = (f_1(\vec{a}), \dots, f_m(\vec{a}))$  then  $f$  is differentiable at  $\vec{a}$  if and only if all  $f_i$  are differentiable at  $\vec{a}$ . (Left as homework)

For simplicity  $n = 2$  by the lemma can just work with single coordinate function, so will take  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^1$ . We will later find out how this generalizes to  $\mathbb{R}^n$ . We are assuming that  $\frac{\partial f}{\partial x}$  is continuous at  $\vec{a}$ . I will write  $f_x$  for now, hence,  $f_x$  is continuous at  $\vec{a}$  and also  $f_y$ . So we are trying to show that

$$\lim_{\vec{h} \rightarrow \vec{0}} \frac{f(\vec{a} + \vec{h}) - f(\vec{a}) - L(\vec{h})}{|\vec{h}|} = \vec{0}$$

$L(\vec{h})$  is what we think as the derivative. Here this  $L(\vec{h})$  should be the matrix

$$L = (f_x(\vec{a}) \quad f_y(\vec{a}))$$

$$\text{LHS} = \frac{|f(\vec{a} + \vec{h}) - f(a_1 + h, a_2) + f(a_1 + h_1, a_2) - f(a_1, a_2) - L(h_1, h_2)|}{\sqrt{h_1^2 + h_2^2}}$$

□

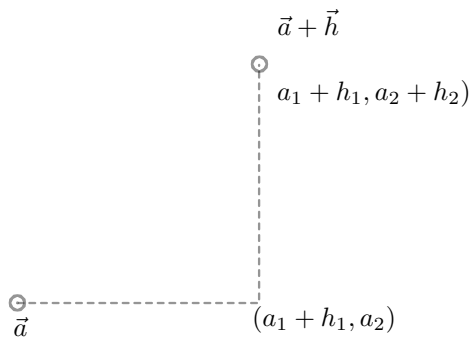


Figure 1: Showing continuity through partial derivatives